

## Program of the entrance exam Wiskunde B

Valid from December 2018

The entrance exam Wiskunde B is taken as a written examination with open questions. The exam time is 3 hours. Information about the exam dates and registration for these exams can be found on [www.ccvx.nl](http://www.ccvx.nl).

The program of the entrance exam Wiskunde B of the CCVW is based on the program wiskunde B of the Dutch VWO for 2019 as published on [www.examenblad.nl](http://www.examenblad.nl). Important difference: **graphing calculators** or any other ICT devices **may not be used** at the entrance exam Wiskunde B. The further determination of the VWO examination program on [www.examenblad.nl](http://www.examenblad.nl) is therefore not applicable.

In this document you will find

- The exam program
- The formula list that is printed on the exam
- Exam supplies
- Elaboration of the exam program in a list of concepts, characteristics and skills
- Overview of algebraic skills
- Recommended learning materials

In entrance exam all calculations must be performed algebraically, the use of a **graphing calculator** or a calculator with the possibility to calculate integrals is therefore **not allowed**.

The use of a standard calculator with exponential, logarithmic and trigonometric functions of a type similar to the Casio fx 82 series and the TI 30 series is permitted.

## Exam program

This is a translation of the official program in Dutch. If there are any discrepancies between the text below and the Dutch version of this text, the Dutch version will prevail.

- 1 The candidate can analyse suitable problem situations in mathematical terms, solve them and translate the result back to the relevant context.
- 2 The candidate masters the mathematical skills appropriate to the examination program, including modelling and algebraizing, organizing and structuring, analytical thinking and problem solving, manipulating formulas, abstracting, and logical reasoning and proofs.
- 3 The candidate can interpret and edit formulas, draw a graph in a coordinate system in a relationship between two variables and determine whether a given formula can be rewritten as a function rule.
- 4 The candidate can draw and recognize graphs of the following standard functions: power functions with rational exponents, exponential functions, logarithmic functions, trigonometric functions and the absolute value function and can name and use the characteristic features of these different types of functions.
- 5 The candidate can draw up function rules, edit them, combine them, draw the corresponding graphs and make qualitative statements about the function and its graph on the basis of a function rule.
- 6 The candidate can conceptually use, draw up and use the inverse of a function.
- 7 The candidate can solve equations, inequalities and systems of two linear equations and interpret the solutions.
- 8 The candidate can determine the asymptotic behaviour of functions and can prove this behaviour with calculation of limits.
- 9 The candidate can interpret the first and second derivative of a function conceptually, can use these to examine the function and can use these in applications.
- 10 The candidate can determine the first and second derivative of functions using the rules for differentiation and can thereby use algebraic techniques.
- 11 The candidate can find the antiderivatives of the standard functions mentioned under 4 and simple combinations thereof (direct integration) and can draw up a definite integral and calculate this exactly in suitable applications.
- 12 The candidate can draw up and edit formulas for periodic phenomena, draw the corresponding graphs, solve equations and use the periodicity with insight, using the formula list where necessary.
- 13 The candidate can investigate and prove geometrical properties of objects, using geometric and algebraic techniques when necessary.
- 14 The candidate can examine the properties and mutual location of points, lines, circles and other suitable figures by means of algebraic representations, can form algebraic representations of figures in a given or self-chosen coordinate system and can use algebraic representations to solve geometrical problems.
- 15 The candidate can derive properties from figures in the plane with the help of vectors and in-products and perform calculations.
- 16 The candidate can apply the indicated techniques in suitable scientific and technical situations.

## Formula list

This list will be printed on the last page of the entrance exam Wiskunde B

$$\sin^2(x) + \cos^2(x) = 1$$

$$\sin(t + u) = \sin t \cos u + \cos t \sin u$$

$$\sin(t - u) = \sin t \cos u - \cos t \sin u$$

$$\cos(t + u) = \cos t \cos u - \sin t \sin u$$

$$\cos(t - u) = \cos t \cos u + \sin t \sin u$$

$$\sin(2t) = 2 \sin(t) \cos(t)$$

$$\cos(2t) = \cos^2(t) - \sin^2(t) = 2 \cos^2(t) - 1 = 1 - 2 \sin^2(t)$$

## Aids required during the entrance exams

To take the exam you must take:

- Identity document. *Your identity document will be inspected during the entrance exam. You should always be able to identify yourself with a valid identity document (passport, Dutch driving licence, Dutch identity card, EU/EEA document, residence document model 2001 types I to IV).*
- Writing utensils. *A pen (not a red one) and a pencil. A pencil may only be used for drawing graphs.*
- A set square and protractor.
- calculator with exponential, logarithmic and goniometric functions. **A *graphic calculator* and/or a calculator with the ability to calculate integrals is *not permitted***; a list of formulae will be provided with the exam. *Other aids, such as a formula sheet, BINAS and table book are NOT permitted.*
- Watch. *It might be a good idea to bring a watch (no smartwatch) to be able to divide your time over the different assignments. You are not allowed to use your mobile phone as a watch.*
- It may also be wise to bring spare batteries for your calculator

Make sure you take the correct calculator with you. If you only have a graphing calculator with you, you will have to take the exam without a calculator.

## Elaboration of the exam program

Below, the exam program is further elaborated in a list of concepts, properties and skills. This list is intended as a support in preparing for the entrance exam, but not as a replacement for the exam program. Although this list has been compiled with the greatest possible care, it may therefore occur that an exam question is not dealt with in this list.

Concept / property / skill	Remark / explanation
<p><b>Standard functions</b></p> <p>Power functions: <math>f(x) = x^n</math></p> <p>Exponential functions: <math>f(x) = a^x</math></p> <p>Logarithmic functions: <math>f(x) = {}^g\log(x)</math></p> <p>The number e and the natural logarithm</p> <p>Trigonometric functions: <math>f(x) = \sin(x)</math>; <math>g(x) = \cos(x)</math></p> <p>Absolute value function: <math>f(x) =  x </math></p>	<p><math>n</math> is a rational number (a fraction)</p> <p><math>a &gt; 0</math></p> <p><math>g &gt; 0</math>; <math>g \neq 1</math>; <math>x &gt; 0</math></p> <p><math>e \approx 2.718282</math>; <math>{}^e\log(x) = \ln(x)</math></p> <p><math>\tan(x) = \frac{\sin(x)}{\cos(x)}</math></p> <p><math> x  = x</math> for <math>x \geq 0</math> <math> x  = -x</math> for <math>x &lt; 0</math></p>
<p><b>Combining functions</b></p> <p>Functions can be added and can be multiplied by a constant</p> <p>Functions can be multiplied and divided</p>	<p><math>f(x) = 4x^4 + 3x^3 + 2x^2 + x + 1</math> is a combination of 5 power functions</p> <p>For example <math>h(x) = x^2 \cdot e^x</math></p>
<p><b>Composition of functions</b></p> <p><math>h(x) = f(g(x))</math></p>	<p><math>f(x) = e^x</math> and <math>g(x) = x^2</math> yields <math>h(x) = e^{x^2}</math></p>
<p><b>Inverse functions</b></p> <p><math>y = f(x) \Leftrightarrow x = f^{inv}(y)</math></p>	<p><math>f(x) = x^3</math> yields <math>f^{inv}(y) = \sqrt[3]{y}</math></p> <p><math>f(x) = g^x</math> yields <math>f^{inv}(y) = {}^g\log(y)</math></p>

<p><b>Domain and Range</b></p> <p>Domain: all permitted values of <math>x</math></p> <p>Range: all possible values of <math>y</math></p> <p>Domain and range are often given in the interval notation</p>	<p><math>f(x) = x^{-1} = \frac{1}{x}</math> does not exist if <math>x = 0</math></p> <p><math>f(x) = x^2</math> yields <math>y = x^2 \geq 0</math></p> <p>You must be able to read this, but you do not have to use it yourself</p>
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<p><b>Powers</b></p> <p><math>a^n</math> is a power with base <math>a</math> and exponent <math>n</math></p>	<p><math>n</math> is a rational number (a fraction)</p>
<p><b>Special exponents</b></p> <p><math>a^2 = a \cdot a</math>; <math>a^3 = a \cdot a \cdot a</math> etc.</p> <p><math>a^1 = a</math></p> <p><math>a^0 = 1</math></p> <p><math>a^{-n} = \frac{1}{a^n} = \left(\frac{1}{a}\right)^n</math></p> <p><math>a^{\frac{1}{n}} = \sqrt[n]{a}</math></p>	<p><math>a \neq 0</math></p> <p><math>a \neq 0</math></p> <p><math>a^{-1} = \frac{1}{a^1} = \frac{1}{a}</math></p> <p><math>n = 2, 3, 4, 5, \dots</math></p> <p><math>a \geq 0</math> for even values of <math>n</math></p> <p><math>a^{\frac{1}{2}} = \sqrt[2]{a} = \sqrt{a}</math></p>
<p><b>Calculation rules for powers</b></p> <p><math>a^m \cdot a^n = a^{m+n}</math></p> <p><math>\frac{a^m}{a^n} = a^{m-n}</math></p> <p><math>(a^m)^n = a^{m \cdot n}</math></p> <p><math>(a \cdot b)^n = a^n \cdot b^n</math></p> <p><math>\left(\frac{a}{b}\right)^n = \frac{a^n}{b^n}</math></p>	<p><math>a^{\frac{m}{n}} = a^{\frac{1}{n} \cdot m} = \left(a^{\frac{1}{n}}\right)^m = \left(\sqrt[n]{a}\right)^m</math></p> <p><math>(a + b)^2 \neq a^2 + b^2</math></p>

<p><b>Power functions</b></p> <p>Standard function: <math>f(x) = x^n</math></p> <p>Constant function: <math>f(x) = c</math></p> <p>Linear functions:  <math>f(x) = ax + b</math></p> <p>Quadratic functions:  <math>f(x) = ax^2 + bx + c</math></p> <p>Root and radical functions:</p> <p>For <math>x \geq 0</math>, <math>f(x) = x^{\frac{1}{2}} = \sqrt{x}</math> is the inverse function of <math>f(x) = x^2</math></p> <p><math>f(x) = x^{\frac{1}{3}} = \sqrt[3]{x}</math> is the inverse function of <math>f(x) = x^3</math></p>	<p>The input variable <math>x</math> is the base</p> <p><math>f(x) = c \cdot x^0</math></p> <p>The graph is a horizontal line</p> <p><math>f(x) = a \cdot x^1 + b \cdot x^0</math></p> <p>The graph is the straight line with equation <math>y = ax + b</math></p> <p>The graph is a parabola with axis of symmetry <math>x = -\frac{b}{2a}</math></p> <p>The graph is opening upward if <math>a &gt; 0</math> and downward if <math>a &lt; 0</math></p> <p>The number of intersections with the <math>x</math>-axis is determined by <math>D = b^2 - 4ac</math></p> <p>Domain: <math>x \geq 0</math>; Range: <math>y \geq 0</math>  The graph is a half (horizontally orientated) parabola</p> <p>Domain: <math>\mathbb{R}</math>; Range: <math>\mathbb{R}</math></p>
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<p><b>Exponential functions</b></p> <p><math>f(x) = a^x</math> with <math>a &gt; 0</math></p> <p>Exponential growth formula with initial value <math>b</math> and growth factor <math>g</math></p> <p>Doubling time, half-life</p>	<p>The input variable <math>x</math> is the exponent</p> <p>If <math>a &gt; 1</math>, <math>f(x)</math> is a convex increasing function with a horizontal asymptote for <math>x \rightarrow -\infty</math></p> <p>If <math>0 &lt; a &lt; 1</math>, <math>f(x)</math> is a convex decreasing function with a horizontal asymptote for <math>x \rightarrow \infty</math></p> <p><math>N(t) = b \cdot g^t</math></p>
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<p><b>Logarithmic functions</b></p> <p><math>l(x) = {}^g\log(x)</math> is the inverse function of <math>f(x) = g^x</math></p> <p><math>{}^g\log(1) = 0; {}^g\log(g) = 1</math></p> <p><math>\log(x) = {}^{10}\log(x)</math></p> <p>Domain: <math>x &gt; 0</math></p>	<p><math>y = {}^g\log(x) \Leftrightarrow g^y = x</math>  <math>e^x = y \Leftrightarrow x = {}^e\log(y) = \ln(y)</math></p> <p><math>\ln(1) = 0; \ln(e) = 1</math></p> <p><math>\log(1) = 0; \log(10) = 1</math></p> <p>The graph has the line <math>x = 0</math> as its vertical asymptote</p> <p>For <math>g &gt; 1</math> the graph is concave and increasing</p> <p>For <math>0 &lt; g &lt; 1</math> the graph is convex and decreasing</p>
<p><b>Calculation rules for logarithms</b></p> <p><math>{}^g\log(a) + {}^g\log(b) = {}^g\log(a \cdot b)</math></p> <p><math>{}^g\log(a) - {}^g\log(b) = {}^g\log\left(\frac{a}{b}\right)</math></p> <p><math>{}^g\log(a^n) = n \cdot {}^g\log(a)</math></p> <p><math>{}^g\log(a) = \frac{{}^p\log(a)}{{}^p\log(g)}</math></p>	<p>These follow from the calculation rules for powers</p> <p>This holds for <i>all</i> numbers <math>n</math></p> <p>Often used with <math>p = 10</math> or <math>p = e</math> to compute logarithms with the log or ln function of a calculator</p>

<p><b>Trigonometry</b></p> <p>Sine, cosine and tangent in a right-angled triangle</p> <p>Angles in a unit circle</p> <p>Angles in degrees and in radians</p> <p>Exact values of the sine and the cosine of standard angles</p> <p>Pythagorean identity</p> <p>Sum formulas</p>	<p><math>180^\circ = \pi \text{ rad}; 1^\circ = \frac{\pi}{180} \text{ rad}</math></p> <p>30-60-90 triangle 45-45-90 triangle</p> <p><math>\cos^2(\alpha) + \sin^2(\alpha) = 1</math></p> <p><i>In the formula list</i></p>
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<p><b>Trigonometric functions</b></p> <p><math>f(x) = \sin(x)</math>; <math>g(x) = \cos(x)</math></p> <p>The period of these standard functions</p> <p>Minima</p> <p>Maxima</p> <p>Zeros</p> <p>Shape of the graph</p> <p>Symmetry relations</p> <p>Horizontal translations</p>	<p>Computations with trigonometric functions are usually in radians</p> <p><math>2\pi</math></p> <p><math>\sin(x) = -1</math> for <math>x = -\frac{1}{2}\pi + k \cdot 2\pi</math>  <math>\cos(x) = -1</math> for <math>x = \pi + k \cdot 2\pi</math></p> <p><math>\sin(x) = 1</math> for <math>x = \frac{1}{2}\pi + k \cdot 2\pi</math>  <math>\cos(x) = 1</math> for <math>x = 0 + k \cdot 2\pi</math></p> <p><math>\sin(x) = 0</math> for <math>x = 0 + k \cdot \pi</math>  <math>\cos(x) = 0</math> for <math>x = \frac{1}{2}\pi + k \cdot \pi</math></p> <p>Sinusoid</p> <p><math>\sin(x) = \sin(\pi - x)</math>  <math>\cos(x) = \cos(-x)</math>  <math>-\sin(x) = \sin(-x) = \sin(\pi + x)</math>  <math>-\cos(x) = \cos(\pi - x) = \cos(\pi + x)</math></p> <p><math>\sin(x) = \cos\left(x - \frac{1}{2}\pi\right)</math>  <math>\cos(x) = \sin\left(x + \frac{1}{2}\pi\right)</math></p>
<p><b>General form of a sinusoid</b></p> <p><math>f(x) = A + B \cdot \sin(C \cdot (x - D))</math></p>	<p><math>A</math> = equilibrium  <math> B </math> = amplitude  <math>C = \frac{2\pi}{\text{period}}</math>  If <math>B &gt; 0</math>, the graph passes the equilibrium in point <math>(D, A)</math> (starting point) and <math>f</math> is increasing in this point</p>
<p><b>Simple harmonic motion</b></p> <p><math>u = a \cdot \sin\left(\frac{2\pi}{T} \cdot t\right)</math></p>	<p><math>a</math> = amplitude  <math>T</math> = time period  <math>f = \frac{1}{T}</math> = frequency</p>



<p><b>Differentiation</b></p> <p>Derivatives of standard functions</p> <p>Various notations for the derivative</p>	<p><math>f(x) = c</math> yields <math>f'(x) = 0</math></p> <p><math>f(x) = x^a</math> yields <math>f'(x) = ax^{a-1}</math></p> <p><math>f(x) = a^x</math> yields <math>f'(x) = a^x \cdot \ln(a)</math></p> <p><math>f(x) = e^x</math> yields <math>f'(x) = e^x</math></p> <p><math>f(x) = \ln(x)</math> yields <math>f'(x) = \frac{1}{x}</math></p> <p><math>f(x) = \sin(x)</math> yields <math>f'(x) = \cos(x)</math></p> <p><math>f(x) = \cos(x)</math> yields <math>f'(x) = -\sin(x)</math></p>
<p><b>Rules for differentiation of combinations of functions</b></p> <p>Constant factor rule</p> <p>Sum rule</p> <p>Product rule</p> <p>Quotient rule</p> <p>Chain rule</p>	<p><math>f(x) = {}^g \log(x) = \frac{\ln(x)}{\ln(g)} = \frac{1}{\ln(g)} \cdot \ln(x)</math></p> <p>yields <math>f'(x) = \frac{1}{\ln(g)} \cdot \frac{1}{x}</math></p> <p>Use the quotient rule to differentiate</p> <p><math>f(x) = \tan(x) = \frac{\sin(x)}{\cos(x)}</math></p>

<p><b>Antidifferentiation and integration</b></p> <p><math>F(x)</math> is antiderivative function of <math>f(x)</math> if <math>F'(x) = f(x)</math></p> <p>If <math>F(x)</math> ean antiderivative of <math>f(x)</math>, then <math>G(x) = F(x) + C</math> is an antiderivative of <math>f(x)</math> too.</p> <p>Definite integral:</p> $\int_a^b f(x) dx = F(b) - F(a)$ <p>Definite integral and area</p>	<p>This is because the constant <math>C</math> vanishes if we differentiate <math>G(x)</math></p> <p>In this formula, <math>F(x)</math> is an antiderivative of <math>f(x)</math></p> <p>If <math>f(x) \geq 0</math> on the interval <math>a \leq x \leq b</math>, then the area of the region bounded by the line <math>x = a</math>, the <math>x</math>-axis, the line <math>x = b</math> and the graph of <math>f</math> is equal to <math>\int_a^b f(x) dx</math></p>
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<p><b>Standard antiderivatives</b></p> <p><math>f(x) = c</math> yields <math>F(x) = cx + C</math></p> <p><math>f(x) = x^a</math> yields <math>F(x) = \frac{1}{a+1}x^{a+1} + C</math></p> <p><math>f(x) = e^x</math> yields <math>F(x) = e^x + C</math></p> <p><math>f(x) = \frac{1}{x}</math> yields <math>F(x) = \ln( x ) + c</math></p> <p><math>f(x) = \sin(x)</math> yields <math>F(x) = -\cos(x) + C</math></p> <p><math>f(x) = \cos(x)</math> yields <math>F(x) = \sin(x) + C</math></p>	<p><math>a \neq -1</math></p> <p>For <math>x &lt; 0</math> this reads <math>F(x) = \ln(-x) + C</math></p>
<p><b>Calculation rules for antidifferentiation of combinations of functions</b></p> <p>Constant factor rule</p> <p>Sum rule</p> <p>Simple chain rule</p>	<p><math>g(x) = c \cdot f(x)</math> yields <math>G(x) = c \cdot F(x)</math></p> <p><math>s(x) = f(x) + g(x)</math> yields <math>S(x) = F(x) + G(x)</math></p> <p><math>g(x) = f(ax + b)</math> yields <math>G(x) = \frac{1}{a} \cdot F(ax + b)</math></p>
<p><b>Calculation rule for definite integrals</b></p>	$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$ <p style="text-align: right;"><math>(a &lt; c &lt; b)</math></p>
<p><b>Applications of definite integrals</b></p> <p>Area of the region with upper boundary <math>f(x)</math> and lower boundary <math>g(x)</math></p> <p>Volume of a solid of revolution with the <math>x</math>-axis as the axis of revolution</p> <p>Volume of a solid of revolution with the <math>y</math>-axis as the axis of revolution</p> <p>Definite integral with variable boundaries</p>	$\int_a^b f(x) - g(x) dx$ $\pi \int_a^b y^2 dx \text{ with } y = f(x)$ $\pi \int_c^d x^2 dy \text{ with } x = f^{inv}(y)$ $g(p) = \int_1^p f(x) dx = F(p) - F(1)$

## Geometry in a Cartesian coordinate system

*In geometry with coordinates, we assume that the units on the axes are equal. This also holds when we examine graphs of functions geometrically.*

### Straight lines

General form of the equation of a straight line:  $mx + ny = c$

Commonly used form:  $y = ax + b$

Slope:  $\frac{\Delta y}{\Delta x} = \frac{y_B - y_A}{x_B - x_A}$

The equation of the line through  $(p, 0)$  and  $(0, q)$  can also be written as  $\frac{x}{p} + \frac{y}{q} = 1$

Not for vertical lines

The slope is equal to  $a$  in the formula  $y = ax + b$

Not possible when  $p = 0$  or  $q = 0$

### Straight lines and angles

The direction angle of a straight line is the angle  $\alpha$  between the line and the  $x$ -axis with  $-90^\circ < \alpha < 90^\circ$

The angle  $\beta$  between two straight lines is the smallest of the angles between these lines in their intersection, so  $0^\circ \leq \beta \leq 90^\circ$

Two lines are perpendicular if the product of their slopes equals  $-1$

$\tan(\alpha) = \text{slope}$

This angle is determined by drawing both lines in a Cartesian plane and indicating the direction angles at the intersection.

*The reverse is also true:*  
If two lines are perpendicular, then the product of their slopes equals  $-1$

<p><b>Perpendicular line and distance</b></p> <p>Perpendicular line</p> <p>Distance between the points <math>A(a_1, a_2)</math> and <math>B(b_1, b_2)</math></p> <p>Projection of a point on a line</p> <p>Distance between a point and a line</p> <p>Distance between two parallel lines</p> <p>Line segment bisector</p> <p>Angle bisector</p>	<p>The slope of the line perpendicular to the line with equation <math>y = ax + b</math> is <math>-\frac{1}{a}</math></p> <p><math> AB  = \sqrt{(b_1 - a_1)^2 + (b_2 - a_2)^2}</math> also noted by <math>d(A, B)</math></p> <p>Distances are measured along perpendicular lines. There is a formula for the distance between a point and a straight line which you may use. However, you do not need to memorize this formula.</p> <p>The line segment bisector of the line segment <math>AB</math> consists of all points <math>P</math> for which <math> PA  =  PB </math></p> <p>The pair of angle bisectors of the lines <math>l</math> and <math>m</math> consists of all points <math>P</math> for which <math>d(P, l) = d(P, m)</math></p>
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<p><b>Geometry in triangles</b></p> <p>Pythagorean theorem</p> <p>Area of a triangle</p> <p>Sum of the angles</p> <p>Law of sines and law of cosines</p> <p>Isosceles triangles</p> <p>Equilateral triangles</p> <p>Similar triangles</p> <p>Median</p> <p>Centroid (centre of mass)</p>	<p><math>\frac{1}{2} \times \text{base} \times \text{height}</math></p> <p>Is always equal to <math>180^\circ</math></p> <p>The angles between the equal sides and the third side are also equal</p> <p>All angles are <math>60^\circ</math></p> <p>Two triangles are similar if the angles of the first triangle are equal to the angles of the second triangle. In that case, the ratios of the lengths of the sides are also equal</p> <p>The centroid divides each median into two parts; the length of the longer part is twice the length of the shorter</p>
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<p><b>Vectors</b></p> <p>A vector indicates a translation over a certain distance in a certain direction</p> <p>The vector that indicates the translation from point <math>A</math> to point <math>B</math> is noted by <math>\overrightarrow{AB}</math></p> <p>Null vector <math>\vec{0}</math></p> <p>Vectors can be added</p> <p>Vectors can be multiplied by a constant</p>	<p>So a vector <math>\vec{v}</math> has a length, indicated by <math> \vec{v} </math>, and a direction</p> <p><math> \vec{0}  = 0</math>; <math>\vec{0}</math> is the only vector that has no direction</p> <p>Head-tail method</p> <p><math>\vec{b} = c \cdot \vec{a}</math> with <math>c &gt; 0</math> has the same direction as <math>\vec{a}</math>; <math> \vec{b}  = c \cdot  \vec{a} </math></p> <p><math>\vec{b} = c \cdot \vec{a}</math> with <math>c &lt; 0</math> has the opposite direction of <math>\vec{a}</math>; <math> \vec{b}  = -c \cdot  \vec{a} </math></p>
<p><b>Vectors with coordinates</b></p> <p><math>\begin{pmatrix} 4 \\ 3 \end{pmatrix}</math> is a vector with coordinates 4 and 3</p> <p><math>\overrightarrow{OA}</math> is the position vector of point <math>A</math></p>	<p><math>\overrightarrow{OA} = \begin{pmatrix} 4 \\ 3 \end{pmatrix}</math> indicates the translation from <math>O(0,0)</math> to <math>A(4,3)</math></p>
<p><b>Computations with coordinates</b></p> <p>Addition</p> <p>Multiplication by a constant</p> <p>The length of a vector</p> <p>The coordinates of the null vector</p> <p>Decomposition along the axes</p>	<p><math>\begin{pmatrix} 4 \\ 3 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 + -1 \\ 3 + 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}</math></p> <p><math>-5 \cdot \begin{pmatrix} -1 \\ 0,2 \end{pmatrix} = \begin{pmatrix} -5 \cdot -1 \\ -5 \cdot 0,2 \end{pmatrix} = \begin{pmatrix} 5 \\ -1 \end{pmatrix}</math></p> <p><math>\left  \begin{pmatrix} 4 \\ 3 \end{pmatrix} \right  = \sqrt{4^2 + 3^2} = 5</math></p> <p><math>\vec{0} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}</math></p> <p><math>\begin{pmatrix} 4 \\ 3 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 3 \end{pmatrix}</math></p>

<p><b>Inner product</b></p> $\vec{a} \cdot \vec{b} =  \vec{a}  \cdot  \vec{b}  \cdot \cos(\alpha)$ <p>If two vectors are perpendicular, their inner product is 0</p>	$\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = a_1 b_1 + a_2 b_2$ $\cos(\alpha) = \frac{a_1 b_1 + a_2 b_2}{ \vec{a}  \cdot  \vec{b} }$ <p><i>The reverse is also true:</i> If the inner product of two vectors is 0, then they are perpendicular (except if one of the vectors is the null vector)</p>
<p><b>Vector representation of a line</b></p> $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} + \lambda \begin{pmatrix} p \\ q \end{pmatrix}$ <p>Position vector <math>\begin{pmatrix} a \\ b \end{pmatrix}</math> Direction vector <math>\begin{pmatrix} p \\ q \end{pmatrix}</math></p> <p>A normal vector of a line is a vector perpendicular to the direction vector of the line</p>	<p>A.k.a. parametric representation</p> <p>The number <math>\lambda</math> is called a parameter</p> <p>The line <math>l</math> with direction vector <math>\begin{pmatrix} p \\ q \end{pmatrix}</math> has normal vector <math>\vec{n}_l = \begin{pmatrix} q \\ -p \end{pmatrix}</math></p> <p>The line <math>m</math> with equation <math>px + qy = c</math> has normal vector <math>\vec{n}_m = \begin{pmatrix} p \\ q \end{pmatrix}</math></p>

<p><b>Geometry in circles</b></p> <p>Equation of the circle with centre <math>M(a, b)</math> and radius <math>r</math>:  <math>(x - a)^2 + (y - b)^2 = r^2</math></p> <p>The equation of a circle can also be written in the form  <math>x^2 + y^2 + px + qy + s = 0</math></p> <p>Computing the intersection(s) with a straight line</p> <p>Tangent line, point of tangency</p> <p>A tangent line to a circle is perpendicular to the radius to the point of tangency</p> <p>Computing the intersections of circles</p> <p>Touching circles</p> <p>Tangent lines through a point <math>P</math> outside the circle</p> <p>Computing the distance between two circles</p> <p>Computing the distance between a line and a circle</p>	<p>Conversion of the first to the second form by expanding brackets</p> <p>Conversion of the second to the first form by completing the square</p> <p>Substitution will yield a quadratic equation with 0, 1 or 2 solutions</p> <p>Slope tangent line <math>\times</math> slope radius = <math>-1</math></p> <p>Elimination of <math>x^2 + y^2</math> yields the equation of the line through the intersections</p> <p>The common tangent line is perpendicular to the line through the centres</p> <p>The points of tangency both have the same distance to <math>P</math></p> <p>Using the line through the centres</p> <p>Using the perpendicular line from the centre of the circle to the line</p>
<p><b>Triangles and circles</b></p> <p>The circumscribed circle of a triangle is the circle that passes through the three vertices</p> <p>The inscribed circle of a triangle has all three sides as tangent lines</p> <p>Thales's theorem</p> <p>Converse of Thales's theorem</p>	<p>The centre is the intersection of the line segment bisectors of the sides</p> <p>The centre is the intersection of the bisectors of the angles</p> <p>If one of the sides of a triangle is a diameter of the circumscribed circle, the opposite angle is a right angle</p> <p>In a right angled triangle, the midpoint of the hypotenuse is the centre of the circumscribed circle</p>

<p><b>Graphs</b></p> <p>Shape of the graphs of standard functions</p>	
<p>Drawing and sketching</p>	<p>When drawing a graph, the value of the numbers on the axes must be indicated, the coordinates of several points must be computed, asymptotes must be indicated if applicable and the domain and the range must be clearly visible.</p> <p>In a sketch of a graph, the shape of the graph, the minima and maxima and the asymptotes must be indicated.</p>
<p><b>Transformations</b></p> <p>Horizontal translation over <math>c</math> units</p> <p>Vertical translation over <math>c</math> units</p> <p>Horizontal multiplication</p> <p>Vertical multiplication</p> <p>Reflexion in the <math>y</math>-axis</p> <p>Reflexion in the <math>x</math>-axis</p>	<p><math>g(x) = f(x - c)</math></p> <p><math>g(x) = f(x) + c</math></p> <p><math>g(x) = f\left(\frac{1}{c} \cdot x\right)</math></p> <p><math>g(x) = c \cdot f(x)</math></p> <p><math>g(x) = f(-x)</math></p> <p><math>g(x) = -f(x)</math></p>
<p><b>Line symmetry in the <math>y</math>-axis</b></p>	<p><math>f(-x) = f(x)</math></p>
<p><b>Point symmetry in the origin</b></p>	<p><math>f(-x) = -f(x)</math></p>
<p><b>Vertical distance between two graphs</b></p>	<p>The distance between the intersections of the graphs of two functions with the vertical line <math>x = p</math> is given by <math> f(p) - g(p) </math></p>



<b>Asymptotes and limits</b>	
Computing limits	Simple examples: $\lim_{x \rightarrow \infty} \frac{1}{x} = 0; \quad \lim_{x \rightarrow 2} \frac{2-x}{4-x^2} = \lim_{x \rightarrow 2} \frac{1}{2+x} = \frac{1}{4}$
Horizontal asymptote	When $\lim_{x \rightarrow \infty} f(x) = c$ or $\lim_{x \rightarrow -\infty} f(x) = c$
Vertical asymptote	When $\lim_{x \uparrow a} f(x) = \infty$ or $\lim_{x \uparrow a} f(x) = -\infty$ or $\lim_{x \downarrow a} f(x) = \infty$ or $\lim_{x \downarrow a} f(x) = -\infty$
Vertical asymptote for a quotient function	$q(x) = \frac{f(x)}{g(x)}$ has a vertical asymptote when $g(x) = 0 \wedge f(x) \neq 0$
Oblique asymptote	When $\lim_{x \rightarrow \infty} (f(x) - (ax + b)) = 0$ or $\lim_{x \rightarrow -\infty} (f(x) - (ax + b)) = 0$
Perforation (removable discontinuity)	When $\lim_{x \uparrow a} f(x) = \lim_{x \downarrow a} f(x)$ , but $f(a)$ does not exist
Jump discontinuity	When $\lim_{x \uparrow a} f(x) \neq \lim_{x \downarrow a} f(x)$

## Applications of the derivative

$f'(a)$  is the slope of the (tangent line to the) graph  $f$  in point  $(a, f(a))$

The angle between two curves in a point  $P$

When  $f'(x) > 0$ , the graph is increasing; when  $f'(x) < 0$ , the graph is decreasing

In a minimum and in a maximum we have  $f'(x) = 0$

Minima and maxima together are called extremes.

The points where the graph has a minimum or a maximum are called the vertices of the graph.

Touching graphs

Perpendicular graphs

In a point where the derivative function has an extreme, the graph has a point of inflexion. In such a point of inflexion we have  $f''(x) = 0$

When  $f'(x) > 0$  and  $f''(x) > 0$ , the graph is increasing and convex (bending upward)

When  $f'(x) > 0$  and  $f''(x) < 0$ , the graph is increasing and concave (bending downward)

When  $f'(x) < 0$  and  $f''(x) > 0$ , the graph is decreasing and convex

When  $f'(x) < 0$  and  $f''(x) < 0$ , the graph is decreasing and concave

Number of intersections of a graph with a horizontal line

$f'(a)$  = slope of the tangent line  
=  $\tan(\text{direction angle})$  in point  $(a, f(a))$

This is the angle between the tangent lines to the curves in point  $P$

The points where  $f$  could have an extreme are computed by solving  $f'(x) = 0$ . After solving this, you have to find the minima and maxima with a sketch of the graph

singular: vertex

$f(x) = g(x)$  and  $f'(x) = g'(x)$

$f(x) = g(x)$  and  $f'(x) \cdot g'(x) = -1$

The points where  $f$  could have a point of inflexion are computed by solving  $f''(x) = 0$ .

*After solving this, you should check whether the derivative indeed has an extreme in such a point, but usually this will be clear from the wording of the question*

Sketch the graph with special attention to the vertices

## Parametric equations

Parametric equations determine the position of a point  $P(x(t), y(t))$  using a parameter  $t$ .

When  $t$  represents time, the parametric equations represent a point moving along a curve, called the path of the point

Vertices of the path

With both  $x(t)$  and  $y(t)$  linear functions, the path is a straight line

The path of a point  $P$  with parametric equations

$$\begin{cases} x(t) = a + r \cos(t) \\ y(t) = b + r \sin(t) \end{cases}$$

Is a circle with centre  $M(a, b)$  and radius  $r$

With both  $x$  and  $y$  periodical functions, the period of the movement of  $P$  is the least common multiple of the periods of  $x$  and  $y$

Velocity vector

Velocity in the  $x$ -direction

Velocity in the  $y$ -direction

Velocity of the moving point

Slope of the tangent to the path in point  $P$

Acceleration vector

Acceleration of the moving point

Example:

$$\begin{cases} x(t) = t^2 \\ y(t) = 2t \end{cases} \text{ or as vector: } \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} t^2 \\ 2t \end{pmatrix}$$

Horizontal tangent line when  $x'(t) \neq 0$  and  $y'(t) = 0$

Vertical tangent line when  $x'(t) = 0$  and  $y'(t) \neq 0$

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} at + b \\ ct + d \end{pmatrix} = \begin{pmatrix} b \\ d \end{pmatrix} + t \begin{pmatrix} a \\ c \end{pmatrix}$$

So the equation of this circle is

$$(x - a)^2 + (y - b)^2 = r^2$$

$$\vec{v} = \begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix}$$

$$\vec{v}_x = \begin{pmatrix} x'(t) \\ 0 \end{pmatrix}$$

$$\vec{v}_y = \begin{pmatrix} 0 \\ y'(t) \end{pmatrix}$$

$$v = |\vec{v}| = \sqrt{(x'(t))^2 + (y'(t))^2}$$

$$\frac{y'(t)}{x'(t)}$$

$$\vec{a} = \begin{pmatrix} x''(t) \\ y''(t) \end{pmatrix}$$

$$\frac{dv}{dt} \text{ with } v \text{ the velocity of the movement}$$

## Algebraic skills

Below an overview of algebraic skills that the candidates for the examination mathematics A of the CCVW must master. Though this list has been compiled with the utmost care too, it may occur that a skill that is included the exam program, is not included in this list

Skill	Remark / explanation
<b>Solving standard equations</b>	
First degree	$ax + b = px + q$
Quadratic	$ax^2 + bx + c = 0$
Power equations with positive even exponents	$x^n = a \Leftrightarrow x = \pm \sqrt[n]{a} \quad (a \geq 0)$
Other power equations	$x^n = a \Leftrightarrow x = a^{\frac{1}{n}}$
Exponential and logarithmic equations that can be solved exactly	${}^g\log(g^n) = a \Leftrightarrow g^n = g^a \Leftrightarrow n = a$
Solving exponential equations using logarithms	$g^x = a \Leftrightarrow x = {}^g\log(a)$
Solving trigonometric equations exactly	$\sin(x) = \sin(A); \cos(x) = \cos(A);$ $\sin(x) = c \text{ en } \cos(x) = c$ met $c = 0, \pm \frac{1}{2}, \pm \frac{1}{2}\sqrt{2}, \pm \frac{1}{2}\sqrt{3}, \pm 1$
Solving trigonometric equations using inverse functions	$\sin(x) = c \Leftrightarrow \sin(x) = \sin(\sin^{-1}(c))$ $\cos(x) = c \Leftrightarrow \cos(x) = \cos(\cos^{-1}(c))$
Equations with absolute values	$ x  = a \Leftrightarrow x = \pm a \quad (a \geq 0)$
<b>Solving inequalities</b>	When solving inequalities graphically, the intersections have to be computed algebraically
<b>Solving systems of equations</b>	By elimination and / or substitution
<b>Finding the equation of a straight line</b>	Determine slope or normal vector and enter these together with the coordinates of a point in one of the standard formulas

<p><b>Rewriting equations and formulas</b></p> <p>Splitting an equation</p> <p>Factorising using a common factor</p> <p>Expanding parentheses</p> <p>Operations with fractions</p> <p>Operations with roots</p>	<p><i>E.g. to rewrite an equation into a standard equation</i></p> $A \cdot B = 0 \Leftrightarrow A = 0 \vee B = 0$ $A^2 = B^2 \Leftrightarrow A = \pm B$ $A \cdot B = A \cdot C \Leftrightarrow A = 0 \vee B = C$ $A \cdot B + A \cdot C = A(B + C)$ $(A + B)(C + D) = AC + AD + BC + BD$ <p>Addition (also of fractions with unlike denominators)</p> <p>Multiplication and division</p> <p>Crosswise multiplication:</p> $\frac{A}{B} = \frac{C}{D} \Leftrightarrow AD = BC \wedge BD \neq 0$ $\sqrt{A} = B \Leftrightarrow A = B^2 \wedge A \geq 0$
<p><b>Solving equations by substitution</b></p>	$x^4 + 4x^2 - 5 = 0 \text{ with } y = x^2$ $e^{2x} + 4e^x - 5 \text{ with } y = e^x$ <p>both yield <math>y^2 + 4y - 5 = 0</math></p>
<p><b>Solving for a variable</b></p>	<p>Solve <math>x</math> from <math>y = f(x)</math></p>
<p><b>Applying calculation rules and properties</b></p>	<p>For powers and logarithms and in trigonometric equations and functions</p>
<p><b>Substitution of formulas into other formulas</b></p>	<p>With correct use of brackets</p>
<p><b>Computations with parameters in function rules</b></p> <p>General</p> <p>The number of intersections with graphs of quadratic functions</p> <p>Curve through the vertices of a graph</p> <p>Touching graphs</p>	<p>In (anti)differentiation, the parameter is a constant, in (systems of) equations, the parameter often is an extra unknown</p> <p><math>D = 0</math> yields an equation for the parameter</p> <p>Eliminate the parameter from the system of equations <math>y = f_p(x)</math> and <math>f'_p(x) = 0</math></p> <p><math>f_p(x) = g(x)</math> and <math>f'_p(x) = g'(x)</math></p>

## **Recommended learning materials**

Unfortunately, as far as we know there are no textbooks in English covering the full program of the Dutch VWO exam wiskunde B. However, there is a textbook that covers most of the calculus topics (functions, (anti)differentiation and integrals):

*Mathematics that works volume 1* (De Gee, ISBN 978-90-5041-167-7)

For other topics, there is a wide range of materials available online, for instance the Kahn academy. You can use Google to find more information on a certain topic.

And last but not least, check the example exams on [www.ccvx.nl](http://www.ccvx.nl)